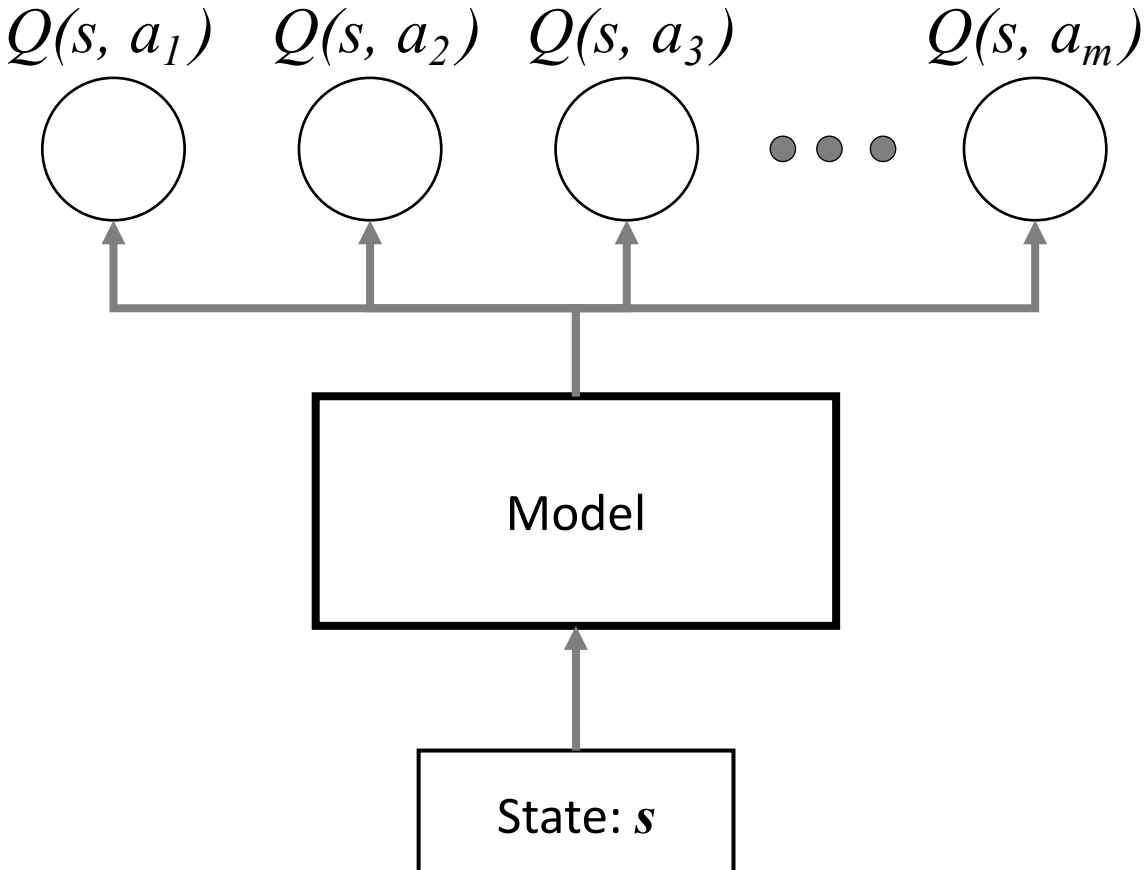
$Q(s, a_1)$
$Q(s, a_2)$
$Q(s, a_3)$
$Q(s, a_m)$
Model
State: s